Carnegie Mellon University

ADVANCED DATABASE SYSTEMS

Parallel Join Algorithms (Sorting)

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PROJECT #2

This Week

→ Status Meetings

Wednesday April 8th

- → Code Review Submission
- → Update Presentation
- \rightarrow Design Document



PARALLEL JOIN ALGORITHMS

Perform a join between two relations on multiple threads simultaneously to speed up operation.

Two main approaches:

- \rightarrow Hash Join
- \rightarrow Sort-Merge Join



TODAY'S AGENDA

Background
Sorting Algorithms
Parallel Sort-Merge Join
Evaluation



Phase #1: Sort

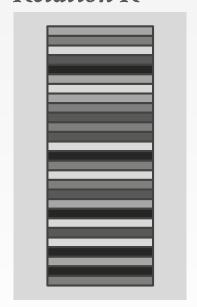
 \rightarrow Sort the tuples of **R** and **S** based on the join key.

Phase #2: Merge

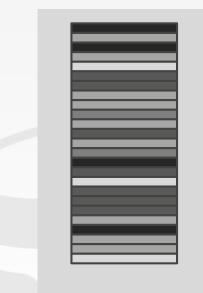
- \rightarrow Scan the sorted relations and compare tuples.
- \rightarrow The outer relation **R** only needs to be scanned once.



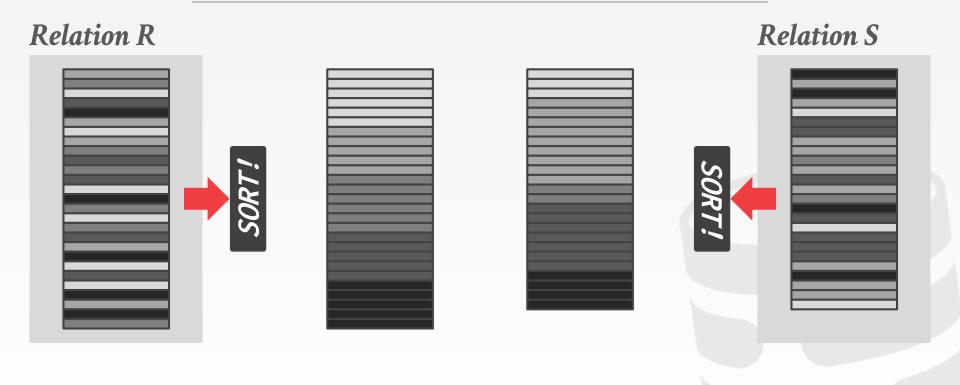
Relation R



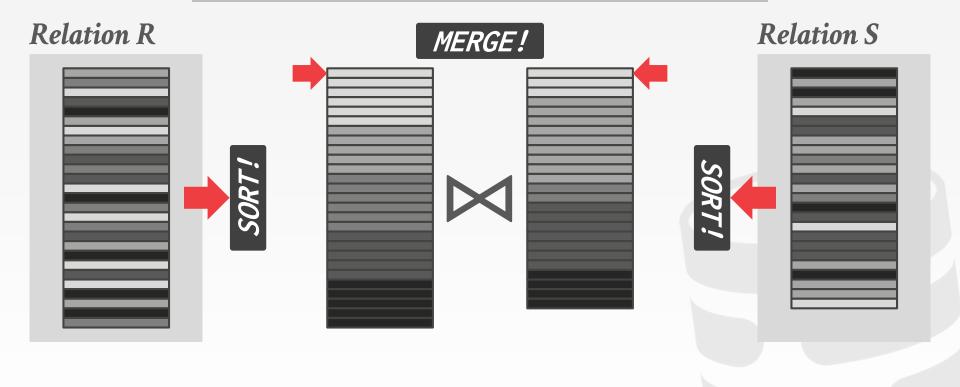
Relation S



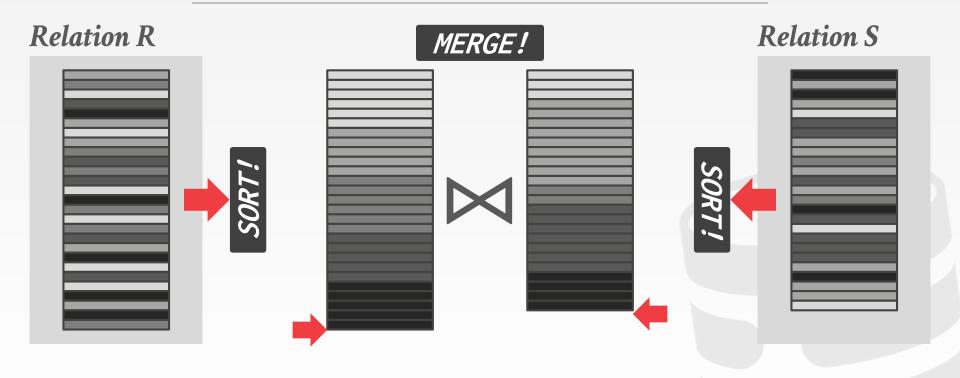














PARALLEL SORT-MERGE JOINS

Sorting is the most expensive part.

Use hardware correctly to speed up the join algorithm as much as possible.

- → Utilize as many CPU cores as possible.
- → Be mindful of NUMA boundaries.
- \rightarrow Use SIMD instructions where applicable.





PARALLEL SORT-MERGE JOIN (R⋈S)

Phase #1: Partitioning (optional)

 \rightarrow Partition **R** and assign them to workers / cores.

Phase #2: Sort

 \rightarrow Sort the tuples of **R** and **S** based on the join key.

Phase #3: Merge

- \rightarrow Scan the sorted relations and compare tuples.
- \rightarrow The outer relation R only needs to be scanned once.



PARTITIONING PHASE

Approach #1: Implicit Partitioning

- → The data was partitioned on the join key when it was loaded into the database.
- \rightarrow No extra pass over the data is needed.

Approach #2: Explicit Partitioning

- → Divide only the outer relation and redistribute among the different CPU cores.
- → Can use the same radix partitioning approach we talked about last time.



SORT PHASE

Create <u>runs</u> of sorted chunks of tuples for both input relations.

It used to be that Quicksort was good enough and it usually still is.

We can explore other methods that try to take advantage of NUMA and parallel architectures ...



CACHE-CONSCIOUS SORTING

Level #1: In-Register Sorting

 \rightarrow Sort runs that fit into CPU registers.

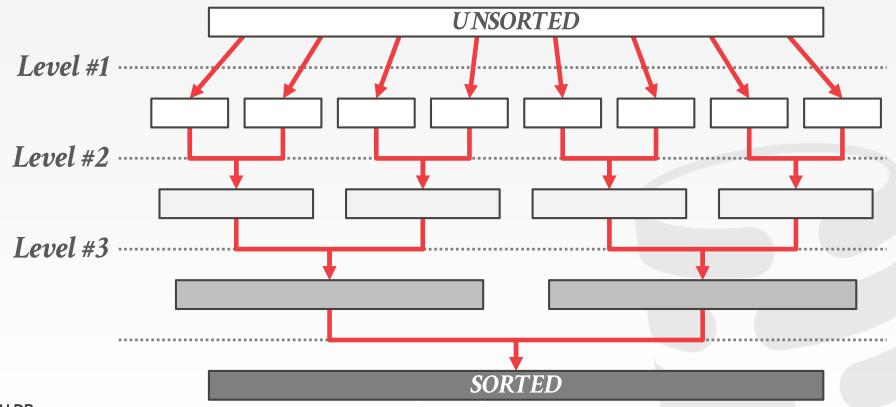
Level #2: In-Cache Sorting

- \rightarrow Merge Level #1 output into runs that fit into CPU caches.
- → Repeat until sorted runs are ½ cache size.

Level #3: Out-of-Cache Sorting

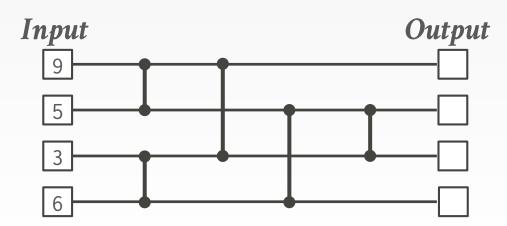
 \rightarrow Used when the runs of Level #2 exceed the size of caches.

CACHE-CONSCIOUS SORTING



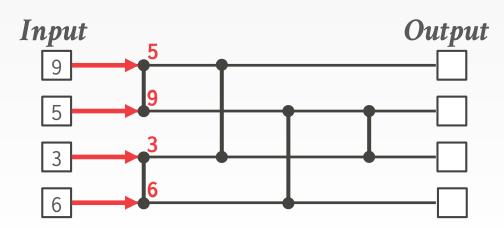


- → Fixed wiring "paths" for lists with the same # of elements.
- → Efficient to execute on modern CPUs because of limited data dependencies and no branches.



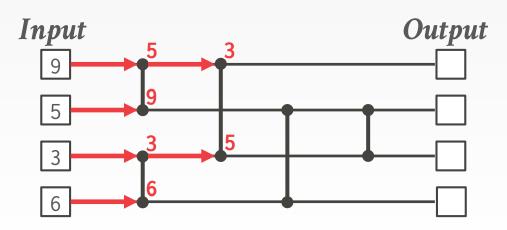


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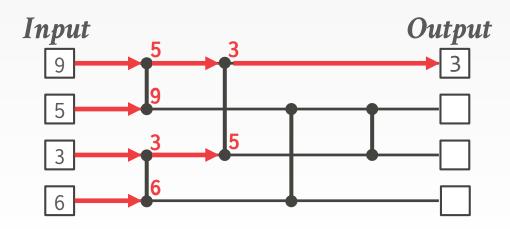


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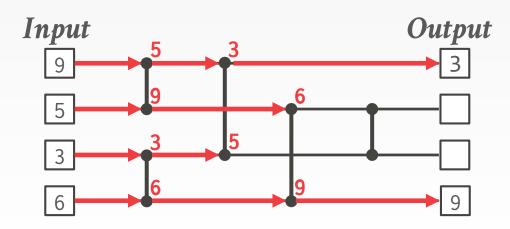


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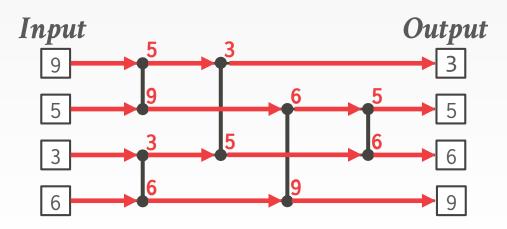


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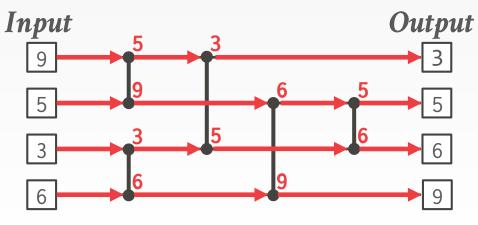


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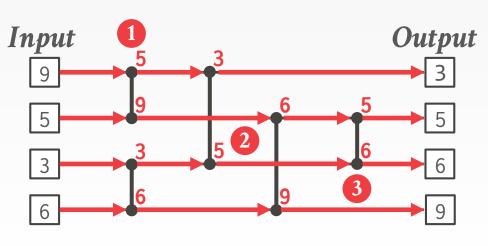
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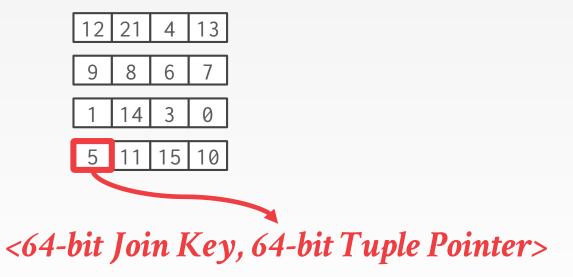
```
wires = [9,5,3,6]
wires[0] = min(wires[0], wires[1])
wires[1] = max(wires[0], wires[1])
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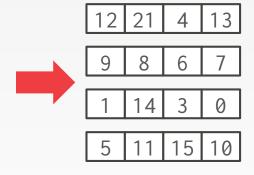
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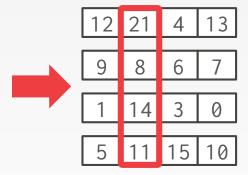


Instructions:

 \rightarrow 4 LOAD



Sort Across Registers

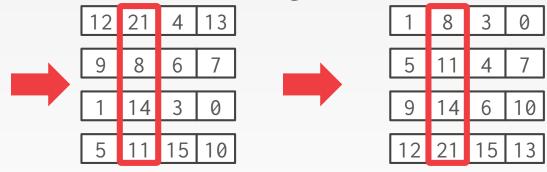


Instructions:

 \rightarrow 4 LOAD



Sort Across Registers



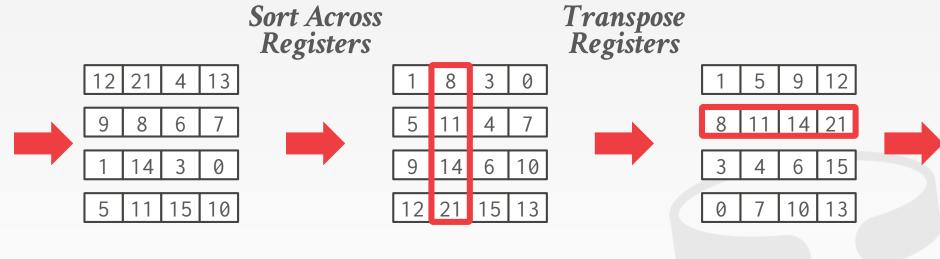
Instructions:

 \rightarrow 4 LOAD

Instructions:

 \rightarrow 10 MIN/MAX





Instructions:

 \rightarrow 4 LOAD

Instructions:

→ 10 MIN/MAX

Instructions:

→ 8 SHUFFLE

 \rightarrow 4 STORE



LEVEL #2 - BITONIC MERGE NETWORK

Like a Sorting Network but it can merge two locally-sorted lists into a globally-sorted list.

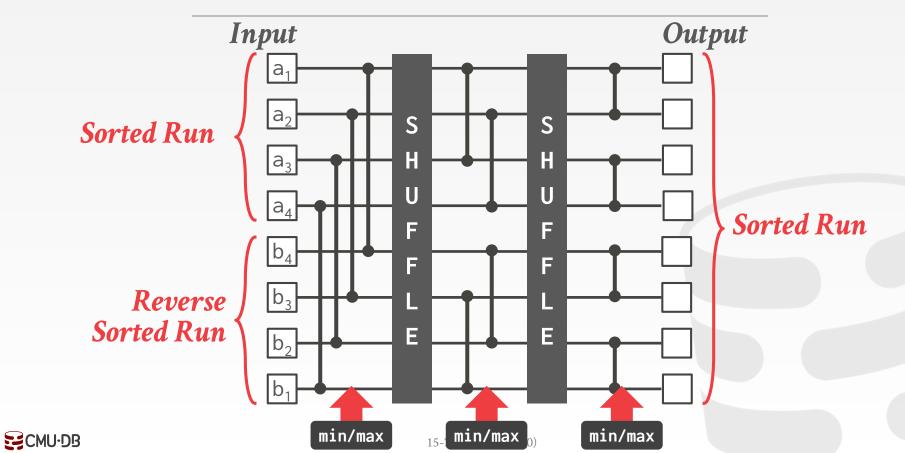
Can expand network to merge progressively larger lists up to ½ LLC size.

Intel's Measurements

 \rightarrow 2.25–3.5× speed-up over SISD implementation.



LEVEL #2 - BITONIC MERGE NETWORK



LEVEL #3 - MULTI-WAY MERGING

Use the Bitonic Merge Networks but split the process up into tasks.

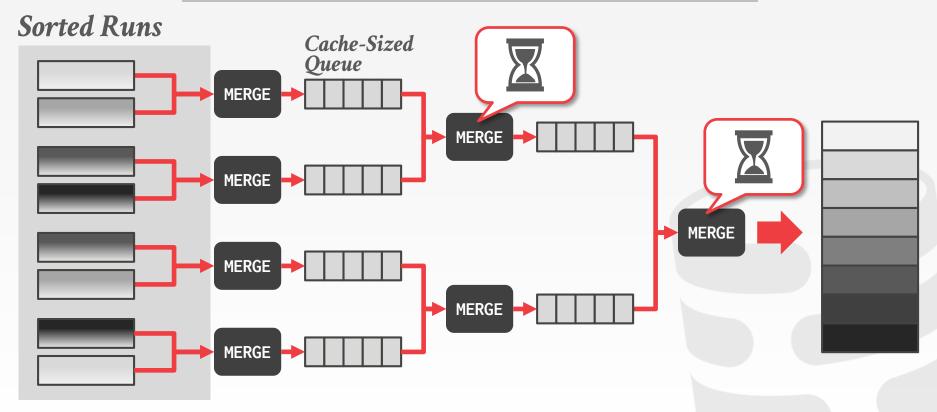
- \rightarrow Still one worker thread per core.
- → Link together tasks with a cache-sized FIFO queue.

A task blocks when either its input queue is empty, or its output queue is full.

Requires more CPU instructions but brings bandwidth and compute into balance.



LEVEL #3 - MULTI-WAY MERGING



IN-PLACE SUPERSCALAR SAMPLESORT

Recursively partition the table by sampling keys to determine partition boundaries.

It copies data into output buffers during the partitioning phases.

But when a buffer gets full, it writes it back into portions of the input array already distributed instead of allocating a new buffer.



MERGE PHASE

Iterate through the outer table and inner table in lockstep and compare join keys.

May need to backtrack if there are duplicates.

Can be done in parallel at the different cores without synchronization if there are separate output buffers.



SORT-MERGE JOIN VARIANTS

Multi-Way Sort-Merge (M-WAY)

Multi-Pass Sort-Merge (M-PASS)

Massively Parallel Sort-Merge (MPSM)



MULTI-WAY SORT-MERGE

Outer Table

- \rightarrow Each core sorts in parallel on local data (levels #1/#2).
- → Redistribute sorted runs across cores using the <u>multi-</u> <u>way merge</u> (level #3).

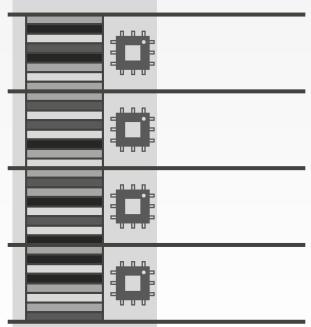
Inner Table

 \rightarrow Same as outer table.

Merge phase is between matching pairs of chunks of outer/inner tables at each core.



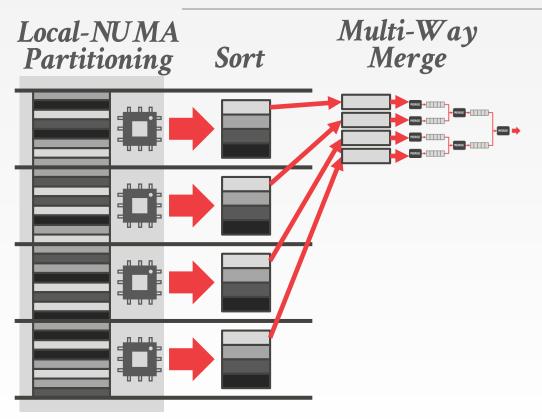
Local-NUMA Partitioning



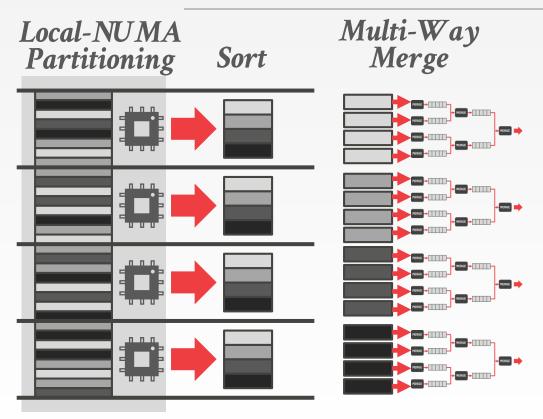


Local-NUMA **Partitioning** Sort

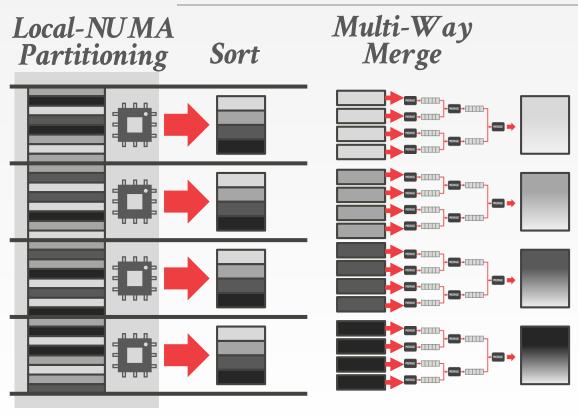




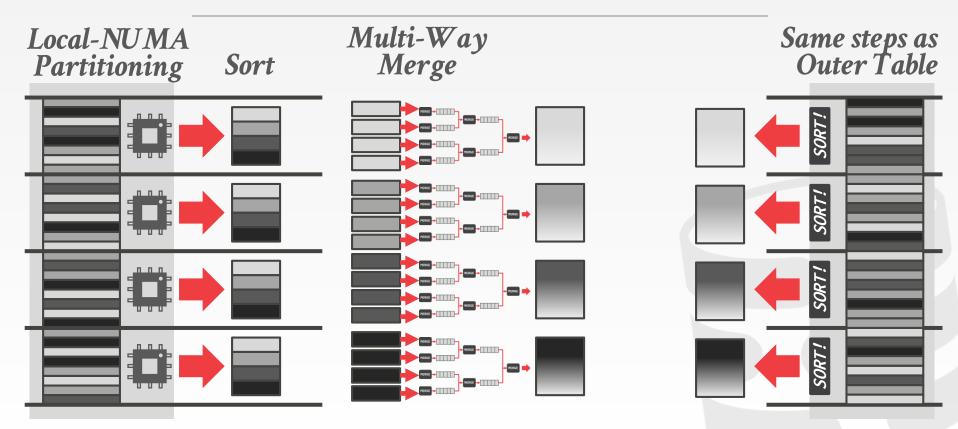




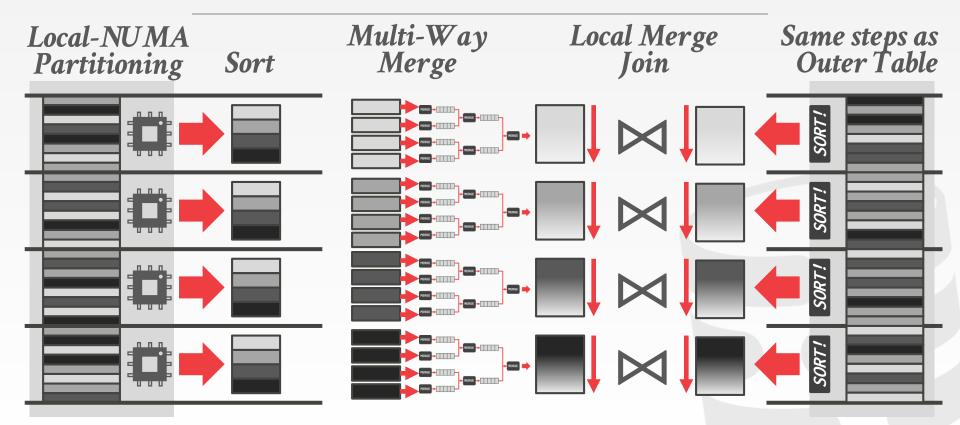














Outer Table

- \rightarrow Same level #1/#2 sorting as Multi-Way.
- → But instead of redistributing, it uses a <u>multi-pass naïve</u> merge on sorted runs.

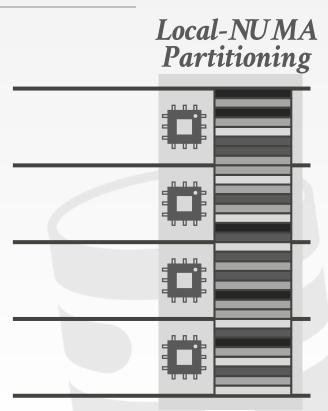
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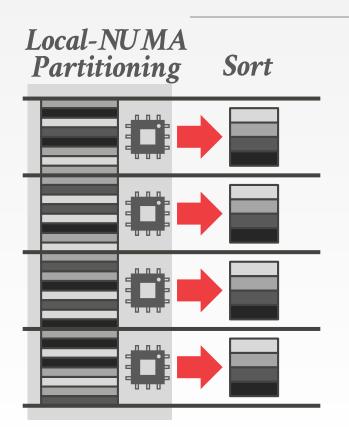
Merge phase is between matching pairs of chunks of outer table and inner table.

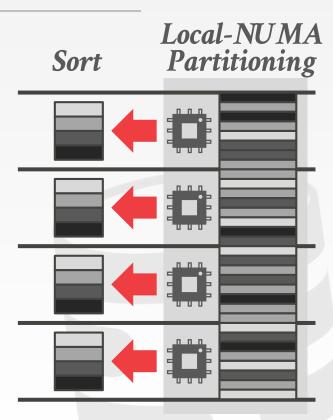


Local-NUMA **Partitioning**

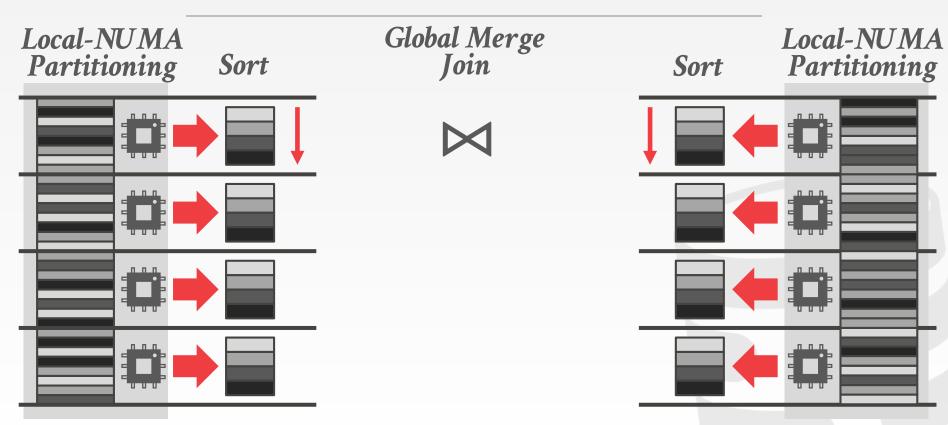




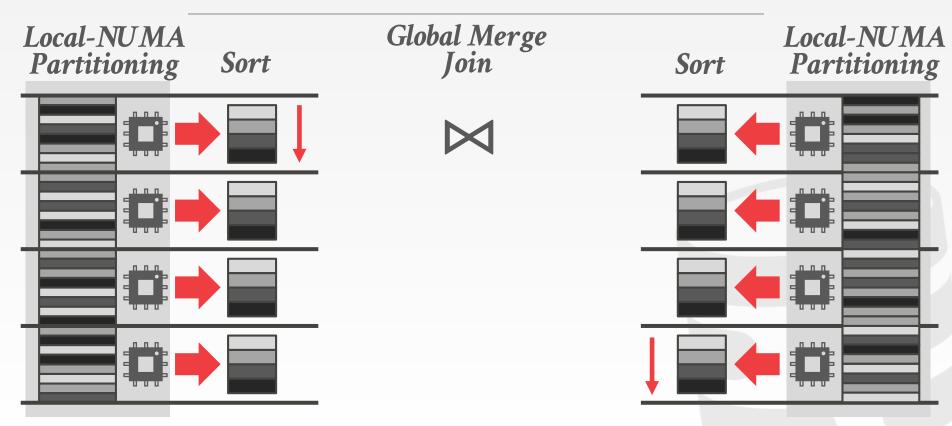














Outer Table

- → Range-partition outer table and redistribute to cores.
- \rightarrow Each core sorts in parallel on their partitions.

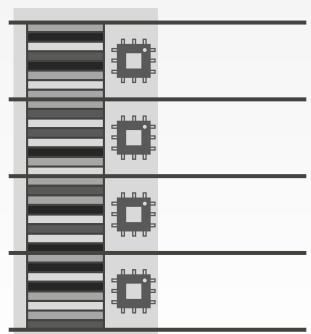
Inner Table

- → Not redistributed like outer table.
- \rightarrow Each core sorts its local data.

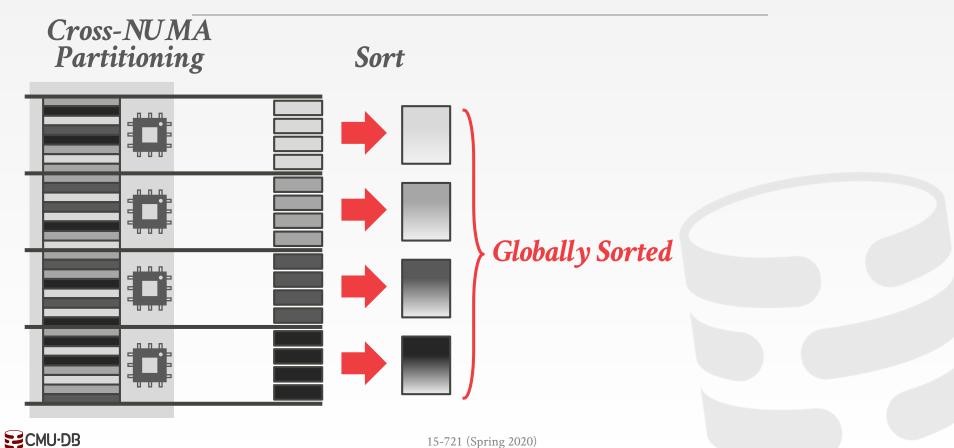
Merge phase is between entire sorted run of outer table and a segment of inner table.

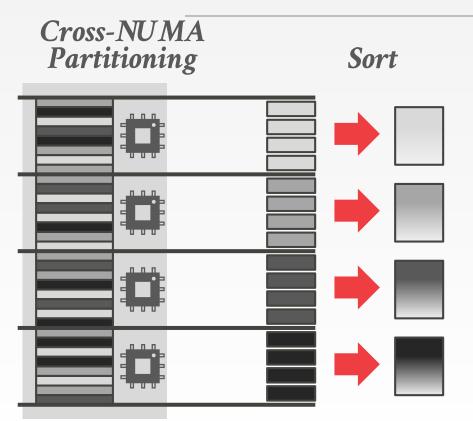


Cross-NUMA Partitioning

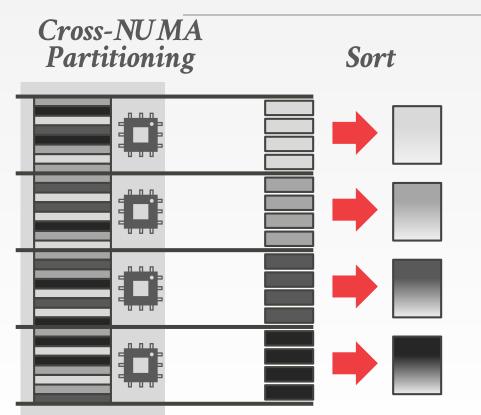


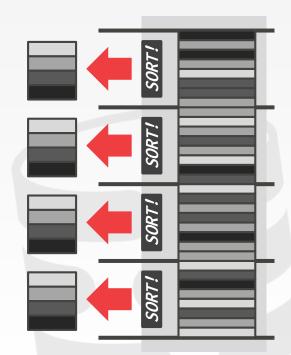




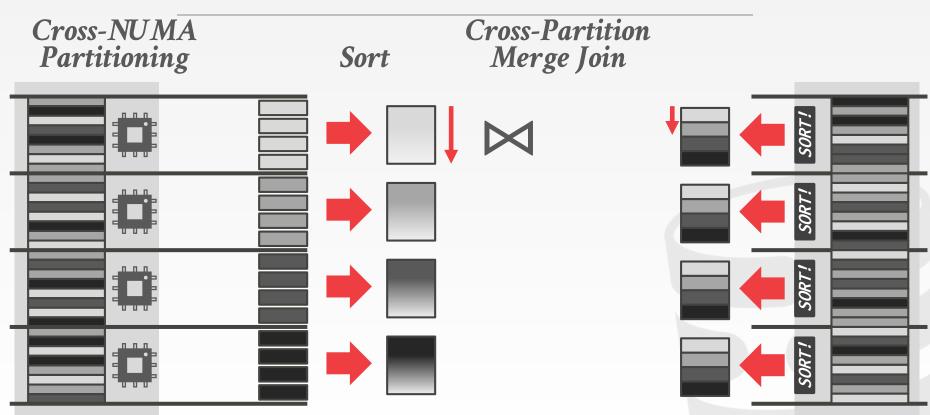




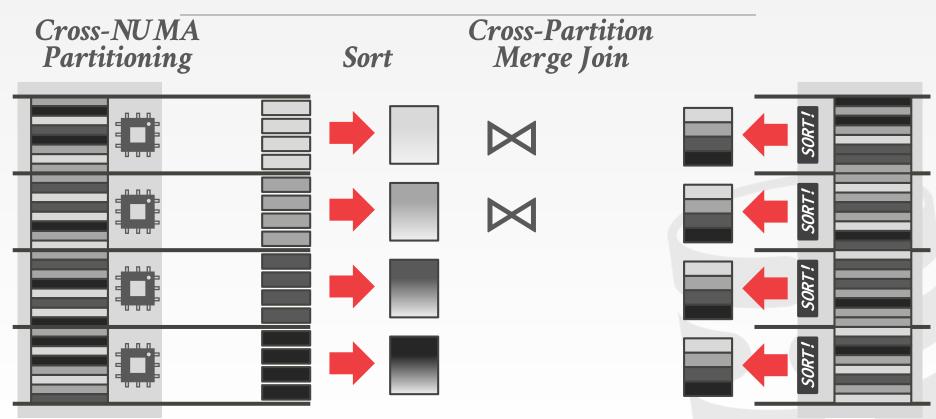




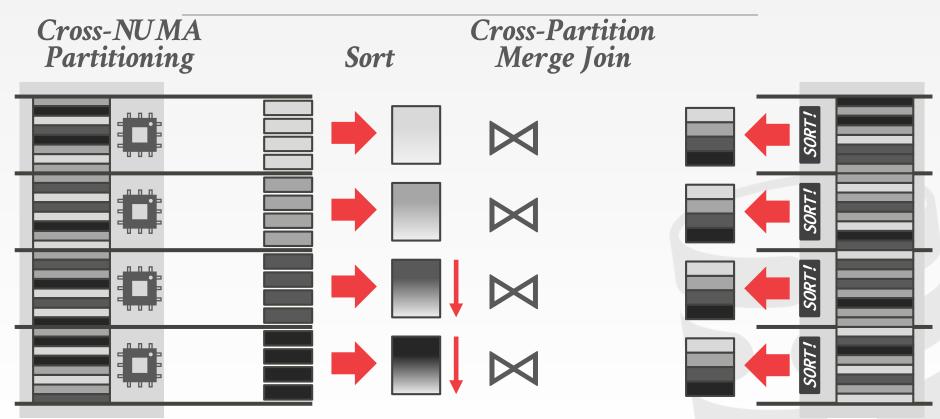














HYPER'S RULES FOR PARALLELIZATION

Rule #1: No random writes to non-local memory

→ Chunk the data, redistribute, and then each core sorts/works on local data.

Rule #2: Only perform sequential reads on non-local memory

→ This allows the hardware prefetcher to hide remote access latency.

Rule #3: No core should ever wait for another

→ Avoid fine-grained latching or sync barriers.

Source: Martina-Cezara Albutiu



EVALUATION

Compare the different join algorithms using a synthetic data set.

- → **Sort-Merge:** M-WAY, M-PASS, MPSM
- → **Hash:** Radix Partitioning

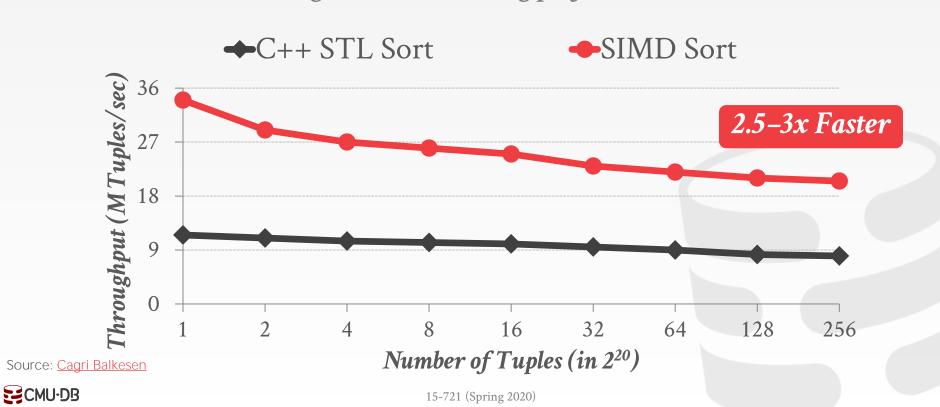
Hardware:

- → 4 Socket Intel Xeon E4640 @ 2.4GHz
- → 8 Cores with 2 Threads Per Core
- \rightarrow 512 GB of DRAM



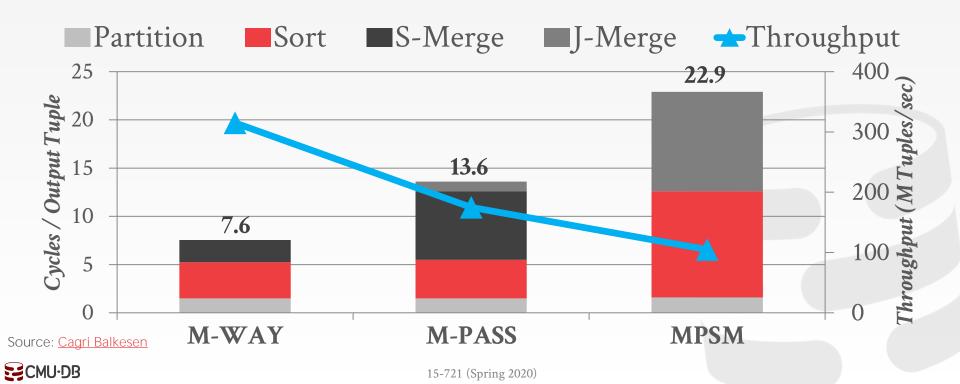
RAW SORTING PERFORMANCE

Single-threaded sorting performance



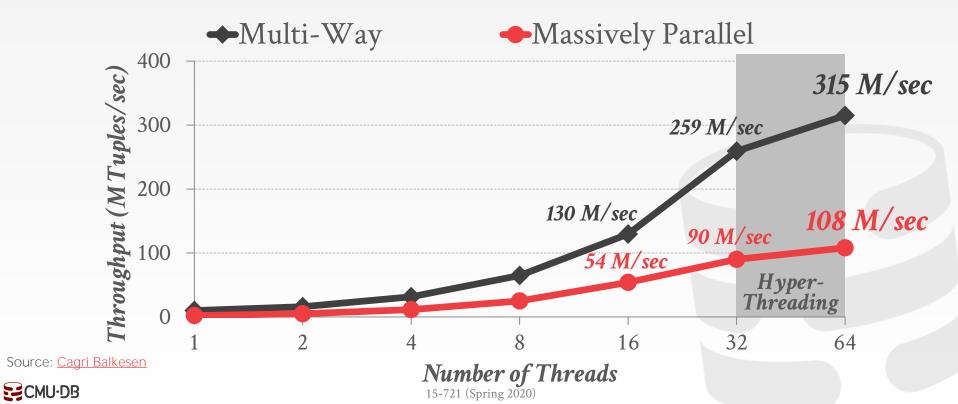
COMPARISON OF SORT-MERGE JOINS

Workload: 1.6B≥128M (8-byte tuples)



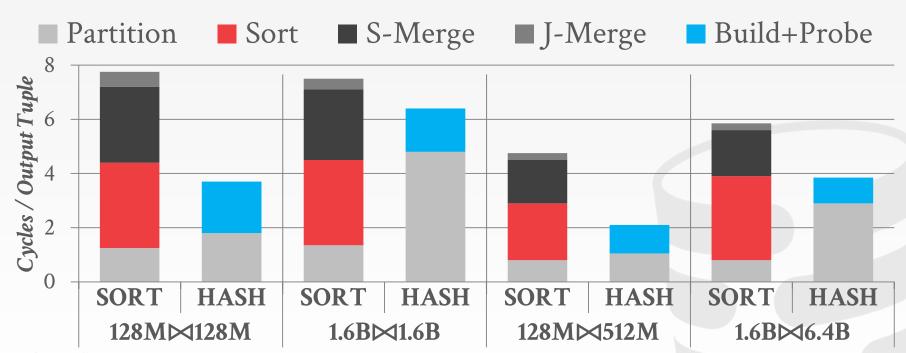
M-WAY JOIN VS. MPSM JOIN

Workload: 1.6B ⋈ 128M (8-byte tuples)



SORT-MERGE JOIN VS. HASH JOIN

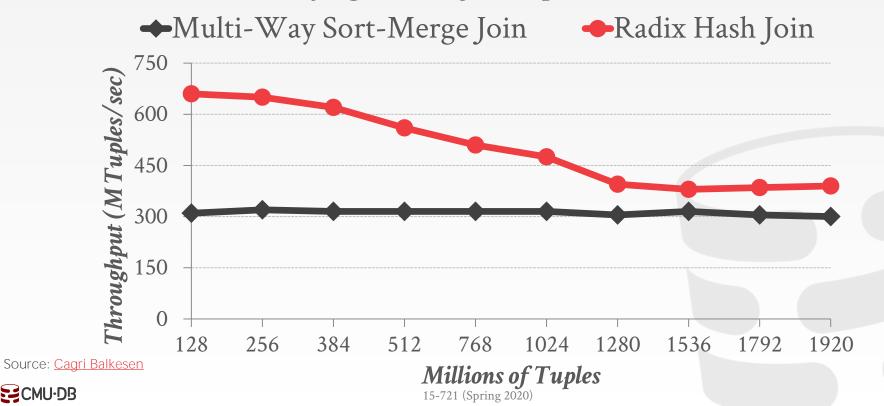
Workload: Different Table Sizes (8-byte tuples)



Source: Cagri Balkesen

SORT-MERGE JOIN VS. HASH JOIN

Varying the size of the input relations



EMU-DB

PARTING THOUGHTS

Both join approaches are equally important. Every serious OLAP DBMS supports both.

We did not consider the impact of queries where the output needs to be sorted.



NEXT CLASS

Optimizers – The Hardest Topic in Databases

