

ADVANCED
DATABASE
SYSTEMS



Databricks Photon / Spark SQL

18

Andy Pavlo
CMU 15-721
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**Carnegie
Mellon
University**



LAST CLASS

Google Dremel is the foundation system architecture for many modern OLAP systems.

ADVENT OF SPARK

High-performance and more expressive replacement for Hadoop from Berkeley.

- Separate compute / storage
- Support for iterative algorithms that make multiple passes on the same data set.

Written in Scala (the hot language in 2010), meaning that it ran on the JVM.

Originally only supported a low-level RDD API.

Added DataFrame API for higher-level abstraction.

SHARK (2013)

Modified version of Facebook's Hive middleware that converted SQL into Spark API programs.

Only supported SQL on data files registered in Hive's catalog. Spark programs could not execute SQL in between API calls.

Shark relied on the Hive query optimizer that was designed for running map-reduce jobs on Hadoop.
→ Spark has a more feature-rich native API.



SPARK SQL (2015)

Row-based SQL engine natively inside of the Spark runtime with Scala-based query codegen.

- In-memory columnar representation for intermediate results as raw byte buffers.
- Dictionary encoding, RLE, bitpacking compressions.
- In-memory shuffle between query stages.

DBMS converts a query's **WHERE** clause expression trees into Scala ASTs. It then compiles these ASTs to generate JVM bytecode.



SPARK SQL (2015)

Row-based SQL engine natively inside of the Spark runtime with Scala-based query codegen

- In-memory columnar representation of query results as raw byte buffers.
- Dictionary encoding, RLE
- In-memory shuffle between

Memory-based Shuffle: Both Spark and Hadoop write map output files to disk, hoping that they will remain in the OS buffer cache when reduce tasks fetch them. In practice, we have found that the extra system calls and file system journaling adds significant overhead. In addition, the inability to control when buffer caches are flushed leads to variability in shuffle tasks. A query's response time is determined by the last task to finish, and thus the increasing variability leads to long-tail latency, which significantly hurts shuffle performance. We modified the shuffle phase to materialize map outputs in memory, with the option to spill them to disk.

DBMS converts a query's parse trees into Scala ASTs. It then compiles these ASTs to generate JVM bytecode.

JVM PROBLEMS

Databricks' workloads were becoming CPU bound.

- Fewer disk stalls because of NVMe SSD caching and adaptive shuffling.
- Better filtering to skip reading data

They found it difficult to optimize their JVM-based Spark SQL execution engine further:

- GC slowdown for heaps larger than 64GB
- JIT codegen limitations for large methods

DATABRICKS PHOTON (2022)

Single-threaded C++ execution engine embedded into Databricks Runtime (DBR) via JNI.

- Overrides existing engine when appropriate.
- Support both Spark's earlier SQL engine and Spark's DataFrame API.
- Seamlessly handle impedance mismatch between row-oriented DBR and column-oriented Photon.

Accelerate execution of query plans over "raw / uncurated" files in a data lake.

DATABRICKS PHOTON (2022)

Photon: A Fast Query Engine for Lakehouse Systems

Alexander Behm, Shoumik Palkar, Utkarsh Agarwal, Timothy Armstrong, David Cashman, Ankur Dave, Todd Greenstein, Shant Hovsepian, Ryan Johnson, Arvind Sai Krishnan, Paul Leventis, Ala Luszczak, Prashanth Menon, Mostafa Mokhtar, Gene Pang, Sameer Paranjpye, Greg Rahn, Bart Samwel, Tom van Bussel, Herman van Hovell, Maryann Xue, Reynold Xin, Matei Zaharia
photon-paper-authors@databricks.com

Databricks Inc.

ABSTRACT

Many organizations are shifting to a data management paradigm called the “Lakehouse,” which implements the functionality of structured data warehouses on top of unstructured data lakes. This

from SQL to machine learning. Traditionally, for the most demanding SQL workloads, enterprises have also moved a curated subset of their data into data warehouses to get high performance, governance and concurrency. However, this two-tier architecture is

DATABRICKS PHOTON

Shared-Disk / Disaggregated Storage

Pull-based Vectorized Query Processing

Precompiled Primitives + Expression Fusion

Shuffle-based Distributed Query Execution

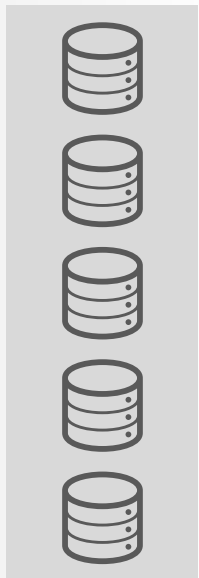
Sort-Merge + Hash Joins

Unified Query Optimizer + Adaptive Optimizations

SPARK: QUERY EXECUTION

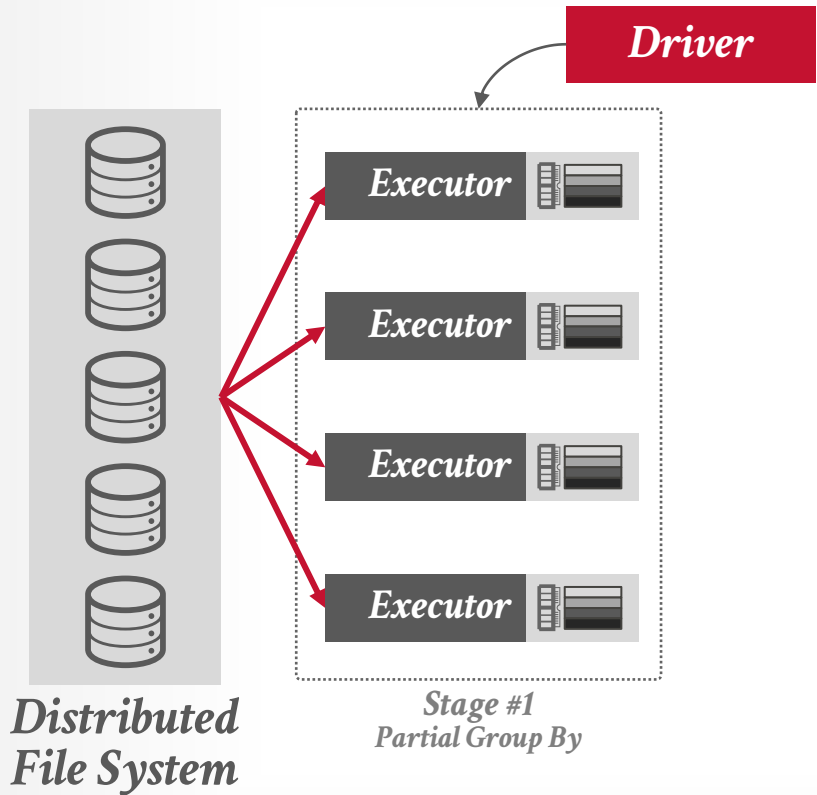
Driver

```
SELECT language, MAX(views)
FROM wikipedia
WHERE title LIKE "%Pavlo%"
GROUP BY 1 ORDER BY 2 DESC
LIMIT 100
```

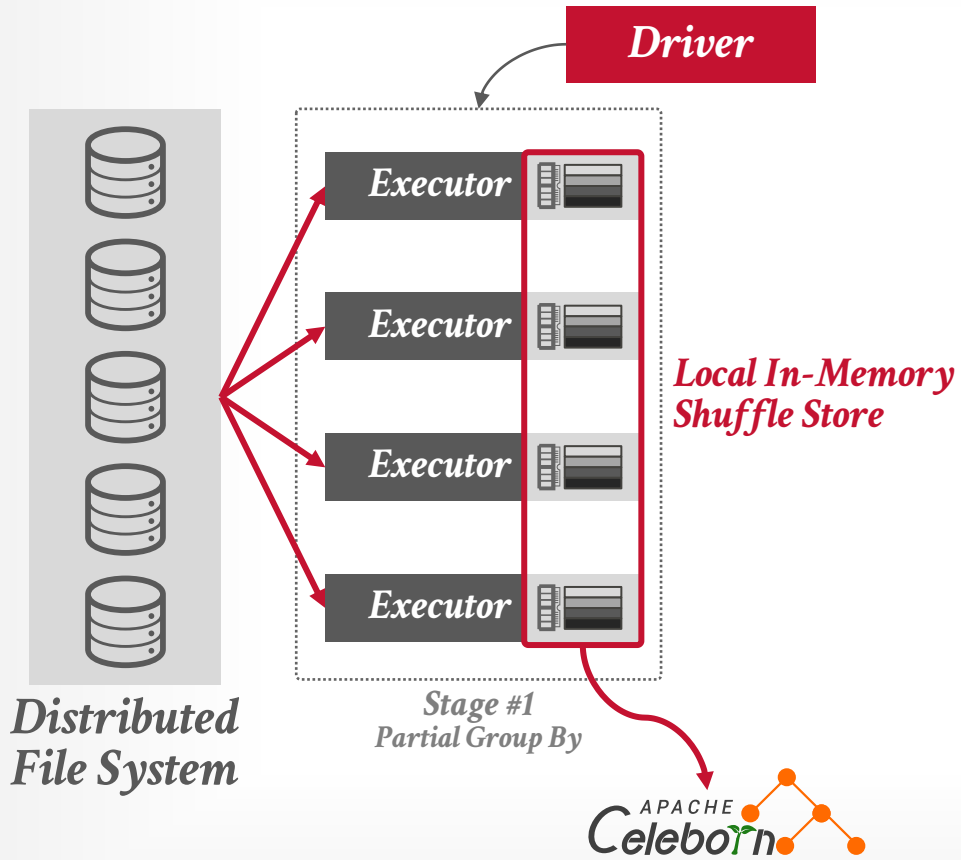


*Distributed
File System*

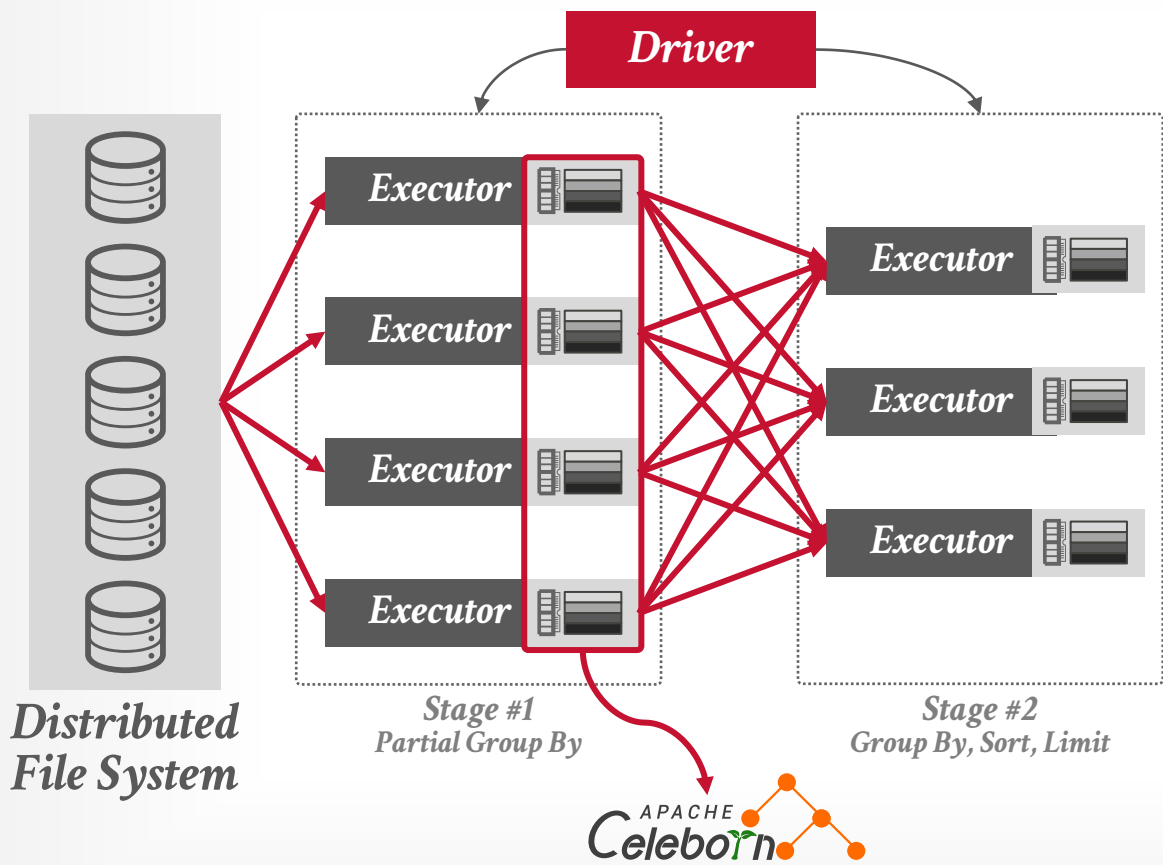
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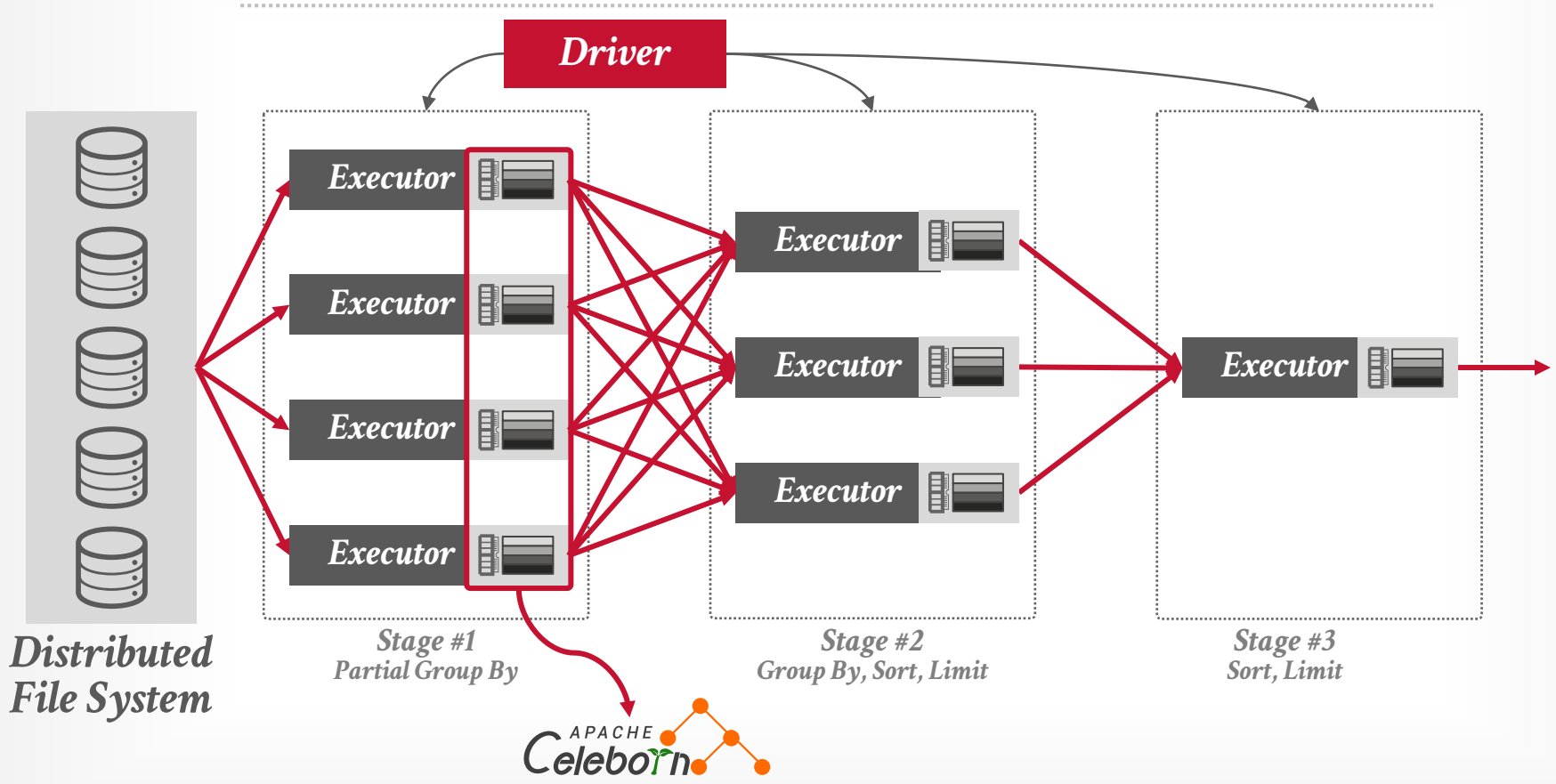
SPARK: QUERY EXECUTION



SPARK: QUERY EXECUTION



SPARK: QUERY EXECUTION



PHOTON: VECTORIZED QUERY PROCESSING

Photon is a pull-based vectorized engine that uses precompiled **operator kernels** (primitives).

→ Converts physical plan into a list of pointers to functions that perform low-level operations on column batches.

Databricks: It is easier to build/maintain a vectorized engine than a JIT engine.

→ Engineers spend more time creating specialized codepaths to get closer to JIT performance.

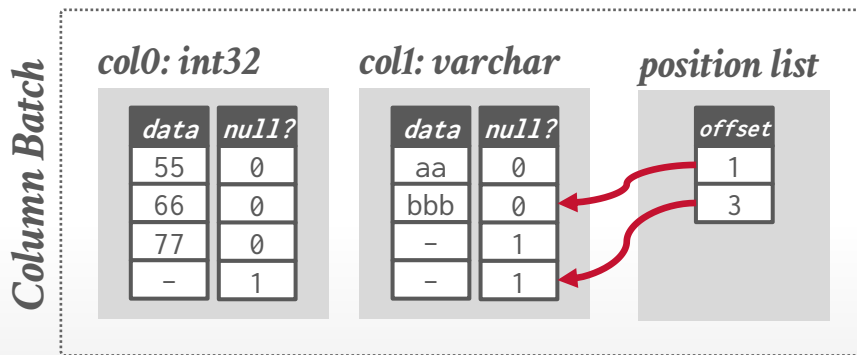
→ With codegen, engineers write tooling and observability hooks instead of writing the engine.

PHOTON: VECTORIZED QUERY PROCESSING

Each **GetNext** invocation on a Photon operator produces a column batch.

- One or more column vectors with a position list vector.
- Each column vector includes a null bitmap.

Databricks: Position list vectors performs better than "active row" bitmap despite indirection.

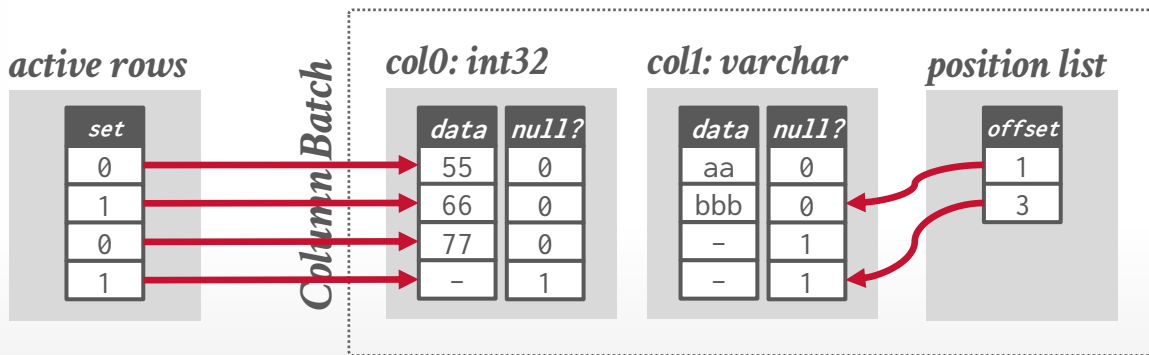


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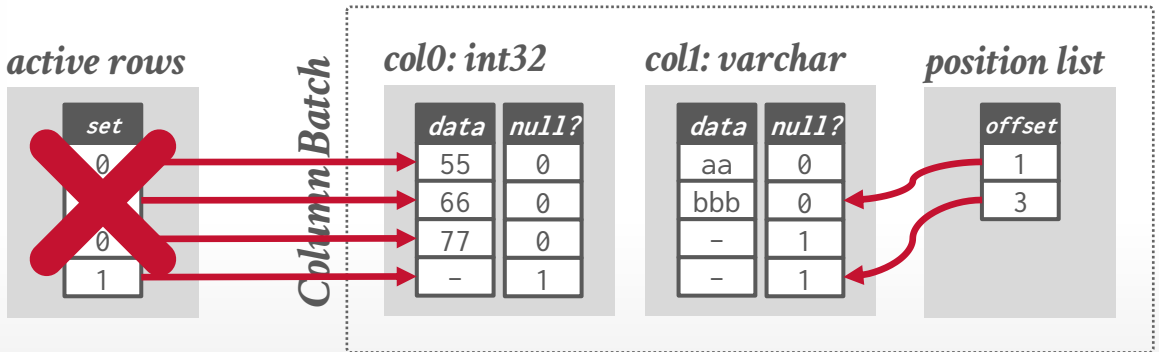
PHOTON: VECTORIZED QUERY PROCESSING

Each **GetNext** invocation on a Photon operator produces a column batch

- One or more column vectors
- Each column vector contains active rows

Databricks: Positional access is faster than "active row"

Another possible design for designating rows as active vs. inactive is a byte vector. This design is more amenable to SIMD, but requires iterating over all rows even in sparse batches. Our experiments showed that in most cases this led to worse overall performance for all but the simplest queries, since loops must iterate over $O(\text{batch size})$ elements instead of $O(\text{active rows})$ elements. **Recent work confirms our conclusions [42].**



ED QUERY PROCESSING

Filter Representation in Vectorized Query Execution

Amadou Ngom*, Prashanth Menon
Matthew Butrovich, Lin Ma, Wan Shen Lim, Todd C. Mowry, Andrew Pavlo
*Massachusetts Institute of Technology, Carnegie Mellon University
(ngom@mit.edu, pmenon@cs.cmu.edu)

Abstract

Advances in memory technology have made it feasible for database management systems (DBMS) to store their working data set in main memory. This trend shifts the bottleneck for query execution from disk accesses to CPU efficiency. One technique to improve CPU efficiency is batch-oriented processing, or vectorization, as it reduces interpretation overhead. For each vector (batch) of tuples, the DBMS must track the set of valid (visible) tuples that survive all previous processing steps. To that end, existing systems employ one of two data structures, or filter representations: selection vectors or bitmaps. In this work, we analyze each approach's strengths or weaknesses and offer recommendations on how to implement vectorized operations. Through a wide range of micro-benchmarks, we determine that the optimal strategy is a function of many factors: the cost of iterating through tuples, the cost of the operation itself, and how amenable it is to SIMD vectorization. Our analysis shows that bitmaps perform better for operations that can be vectorized using SIMD instructions and that selection vectors perform better on all other operations due to cheaper iteration logic.

ACM Reference Format:

Amadou Ngom*, Prashanth Menon and Matthew Butrovich, Lin Ma, Wan Shen Lim, Todd C. Mowry, Andrew Pavlo. 2021. Filter Representation in Vectorized Query Execution. In *International Workshop on Data Management on New Hardware (DAMON '21)*, June 20–25, 2021, Virtual Event, China. ACM, New York, NY, USA, 7 pages. <https://doi.org/10.1145/3465998.3466009>

1 Introduction

Modern DBMSs utilize the vectorized processing model pioneered by Vectorwise [17] to improve query execution performance. In this model, relational operators implement a uniform interface to iterate over its results in a Volcano-style manner [3]. However, unlike the original Volcano model, in a vectorized engine, relational operators exchange small vectors of typically 1–2k tuples in each invocation of the iterator. This simple enhancement (1) amortizes the iteration overhead across all tuples in the vector and (2) maximizes computation on tuple data while it is in the CPU's cache.

Vectorized relational operators exchange batches of tuple where each tuple attribute is stored separately in a compact vector. For instance, a filter operator applies a predicate on each input tuple and copies its attributes into an output vector if successful. This

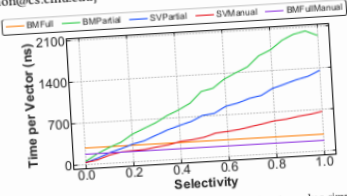


Figure 1: Motivating Example – We evaluate the time to apply a simple predicate filtering an arithmetic column with a constant value.

approach incurs memory overhead due to data copying. A common technique to overcome this is to augment batches with a data structure that logically masks out invalid tuples (i.e., a logical filter). We refer to this data structure as a *filter representation*. Two common representations are (1) Selection Vectors (SVs) and (2) Bitmaps (BMs). A SV is a dense sorted list of tuple identifiers (TID) indicating which tuples in the batch are valid during processing. With BMs, each tuple in the batch is assigned a positionally aligned bit; valid tuples have their bit set to 1. The DBMS marks tuples as invalid by modifying the filter representation alone without copying data.

Interestingly, previous works choose a representation strategy without providing a clear (or empirical) justification. Vectorwise and its derivatives rely selection vectors [6, 14, 15, 17]. IBM DB2's BLU [12] and the more recent VIP [11] rely on bitmaps for the intermediary results of a table scan's filters and selection vectors for better performance and dynamically choosing between them results in better performance than static implementations. Depending on the specific primitive and the selectivity (i.e., the ratio of selected tuples) of its input vector, selection vectors can outperform bitmaps and vice-versa.

To illustrate the need for a deeper exploration of the impact of a chosen filter representation strategy, we present an experiment that measures the performance of evaluating a WHERE during a sequential table scan over a table composed of a single 64-bit integer column. For this experiment, we generate the column's data using a uniform distribution, and vary the input filter's selectivity between 0 and 1. We defer the full description of our experimental setup to Section 3.

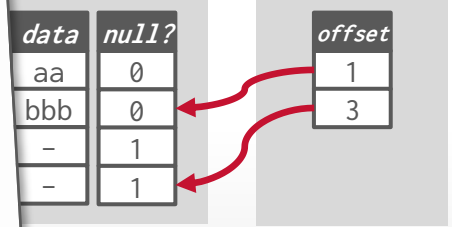
We implement and measure five different execution strategies. BMPartial, BMFull, and BMFullManual all use bitmaps. BMPartial applies the operation only on selected tuples, while BMFull applies it on all tuples. Likewise, BMFullManual uses a hand-written SIMD kernel to apply the operation to all tuples in each vector. SVPartial

on a Photon operator

Other possible design for designating rows as active vs. inactive as a byte vector. This design is more amenable to SIMD, experiments showed that in most cases this led to worse overall performance for all but the simplest queries, since loops must iterate over $O(\text{batch size})$ elements instead of $O(\text{active rows})$ elements. **Work confirms our conclusions [42].**

l1: varchar

position list



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ACM ISBN 978-1-4503-8556-3/21/06.
<https://doi.org/10.1145/3465998.3466009>

PHOTON: VECTORIZED QUERY PROCESSING

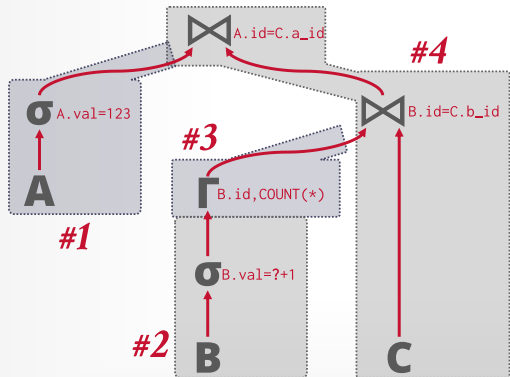
Photon does not use HyPer-style operator fusion so that the DBMS can collect isolated metrics per operator to help users understand query behavior.
→ Vertical fusion over multiple operators in a pipeline.

Instead, Photon's engineers fuse expression primitives to avoid excessive function calls.
→ Horizontal fusion within a single operator.

HYPER: OPERATOR FUSION

```

SELECT *
FROM A, C,
  (SELECT B.id, COUNT(*)
   FROM B
   WHERE B.val = ? + 1
   GROUP BY B.id) AS B
WHERE A.val = 123
  AND A.id = C.a_id
  AND B.id = C.b_id
  
```



Generated Query Plan

```

for t in A:
  if t.val == 123:
    Materialize t in HashTable ⋈(A.id=C.a_id)

for t in B:
  if t.val == <param> + 1:
    Aggregate t in HashTable Γ(B.id)

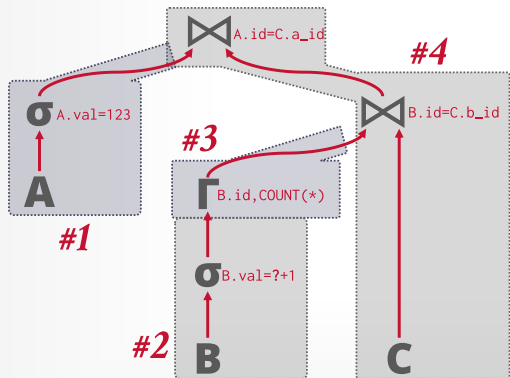
for t in Γ(B.id):
  Materialize t in HashTable ⋈(B.id=C.b_id)

for t3 in C:
  for t2 in ⋈(B.id=C.b_id):
    for t1 in ⋈(A.id=C.a_id):
      emit(t1⋈t2⋈t3)
  
```

HYPER: OPERATOR FUSION

```

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   GROUP BY B.id) AS B
WHERE A.val = 123
AND A.id = C.a_id
AND B.id = C.b_id
  
```



Generated Query Plan

```

#1 {
  for t in A:
    if t.val == 123:
      Materialize t in HashTable  $\bowtie(A.id=C.a_id)$ 
}

#2 {
  for t in B:
    if t.val == <param> + 1:
      Aggregate t in HashTable  $\Gamma(B.id)$ 
}

#3 {
  for t in  $\Gamma(B.id)$ :
    Materialize t in HashTable  $\bowtie(B.id=C.b_id)$ 
}

#4 {
  for t3 in C:
    for t2 in  $\bowtie(B.id=C.b_id)$ :
      for t1 in  $\bowtie(A.id=C.a_id)$ :
        emit(t1  $\bowtie$  t2  $\bowtie$  t3)
}
  
```

PHOTON: EXPRESSION FUSION

```
SELECT * FROM foo
WHERE cdate BETWEEN '2024-01-01' AND '2024-04-01';
```


PHOTON: EXPRESSION FUSION

```
SELECT * FROM XXX
WHERE cdate >= '2024-01-01'
AND cdate <= '2024-04-01';
```

σ cdate >= '2024-01-01'
AND
cdate <= '2024-04-01'

XXX

```
vec<offset> sel_geq_date(vec<date> batch, date val) {
  vec<offset> positions;
  for (offset i = 0; i < batch.size(); i++)
    if (batch[i] >= val) positions.append(i);
  return (positions);
}
```

```
vec<offset> sel_leq_date(vec<date> batch, date val) {
  vec<offset> positions;
  for (offset i = 0; i < batch.size(); i++)
    if (batch[i] <= val) positions.append(i);
  return (positions);
}
```

PHOTON: EXPRESSION FUSION

```
SELECT * FROM xxx
WHERE cdate >= '2024-01-01'
      AND cdate <= '2024-04-01';
```

 σ

```
cdate >= '2024-01-01'
AND
cdate <= '2024-04-01'
```

XXX

```
vec<offset> sel_between_dates(vec<date> batch,
                              date low, date high) {
    vec<offset> positions;
    for (offset i = 0; i < batch.size(); i++)
        if (batch[i] >= low && batch[i] <= high)
            positions.append(i);
    return (positions);
}
```

MEMORY MANAGEMENT

All memory allocations go to memory pool managed by the DBR in the JVM.

→ Single source of truth for runtime memory usage.

Because there are no data statistics, the DBMS has to be more dynamic in its memory allocations.

→ Instead of operators spilling its own memory to disk when it runs out of space, operators request for more memory from the manager who then decides what operators to release memory.

→ Simple heuristic that releases memory from the operator that has the least allocated but enough to satisfy request.

CATALYST QUERY OPTIMIZER

Cascades-style query optimizer for Spark SQL written in Scala that executes transformations in pre-defined stages similar to Microsoft SQL Server.

Three type of transformations:

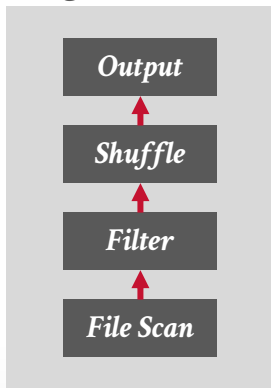
- **Logical**→**Logical** ("Analysis & Optimization Rules")
- **Logical**→**Physical** ("Strategies")
- **Physical**→**Physical** ("Preparation Rules")

PHOTON: PHYSICAL PLAN TRANSFORMATION

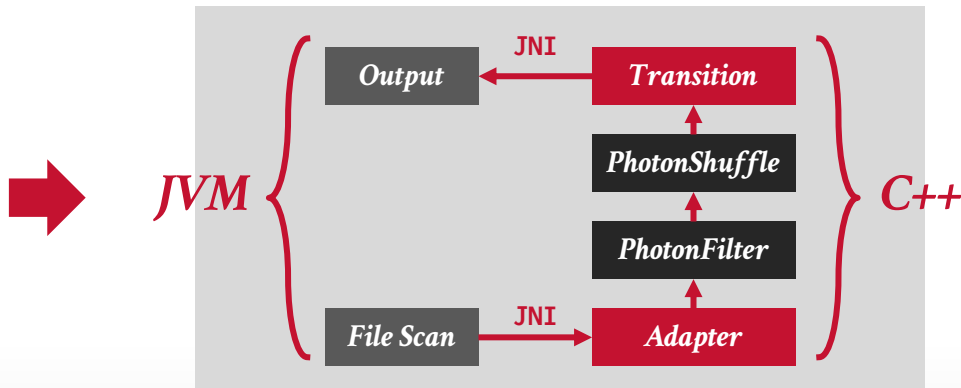
Traverse the original query plan bottoms-up to convert it to a Photon-specific physical plan.

→ New Goal: Limit the number of runtime switches between old engine (Java) and new engine (C++).

Original Plan



New Plan



RUNTIME ADAPTIVITY

Query-Level Adaptivity (Macro)

- Leverage statistics collected at the end of each shuffle stage to re-evaluate previous query plan decisions
- This is provided by DBR wrapper.
- Similar to the Dremel approach we discussed last class.

Batch-Level Adaptivity (Micro)

- Specialized code paths inside of an operator to handle the contents of a single tuple batch.
- This is done by Photon during query execution.
- Similar to Velox optimizations discussed in [Lecture #05](#).

SPARK: ADAPTIVE QUERY OPTIMIZATION

Spark changes the query plan before a stages starts based on observations from the preceding stage.

→ Avoids the problem of optimizer making decisions with inaccurate (or non-existing) data statistics.

Optimization Examples:

→ Dynamically switch between shuffle vs. broadcast join.

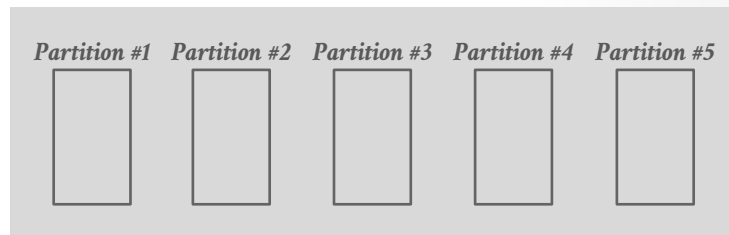
→ Dynamically coalesce partitions

→ Dynamically optimize skewed joins

SPARK: PARTITION COALESCING

Spark (over-)allocates a large number of shuffle partitions for each stage.
→ Number needs to be large enough to avoid one partitioning from filling up too much.

After the shuffle completes, the DBMS then combines underutilized using heuristics.

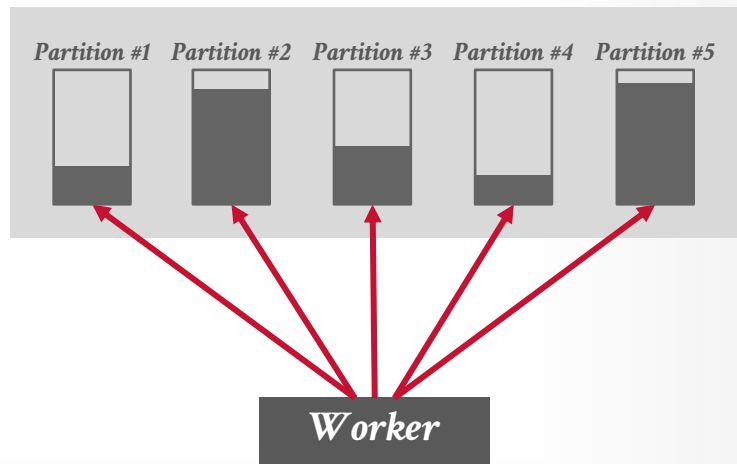


Worker

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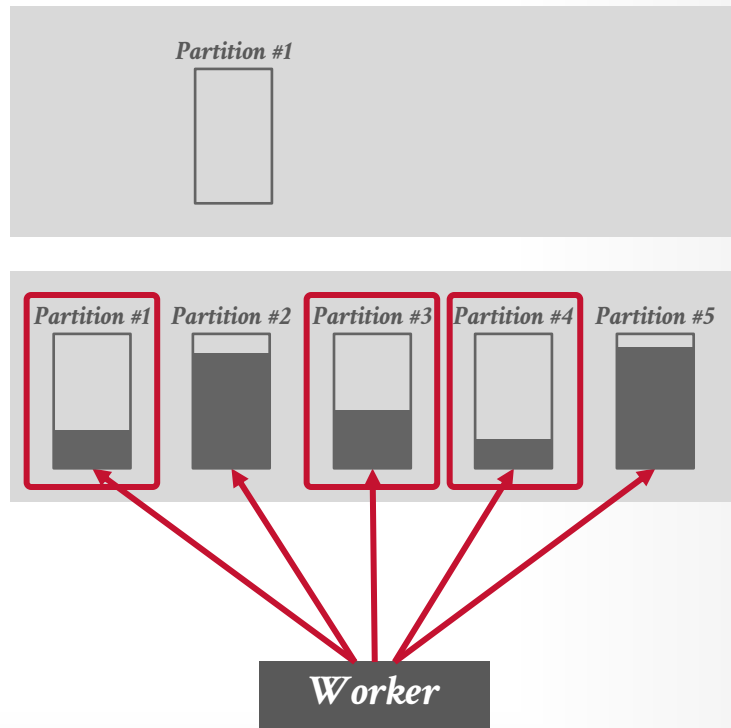
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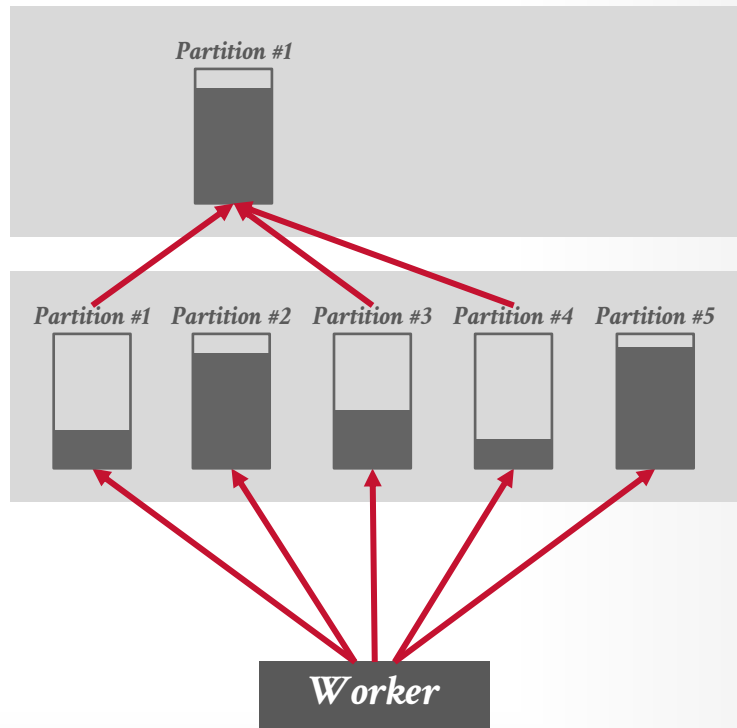
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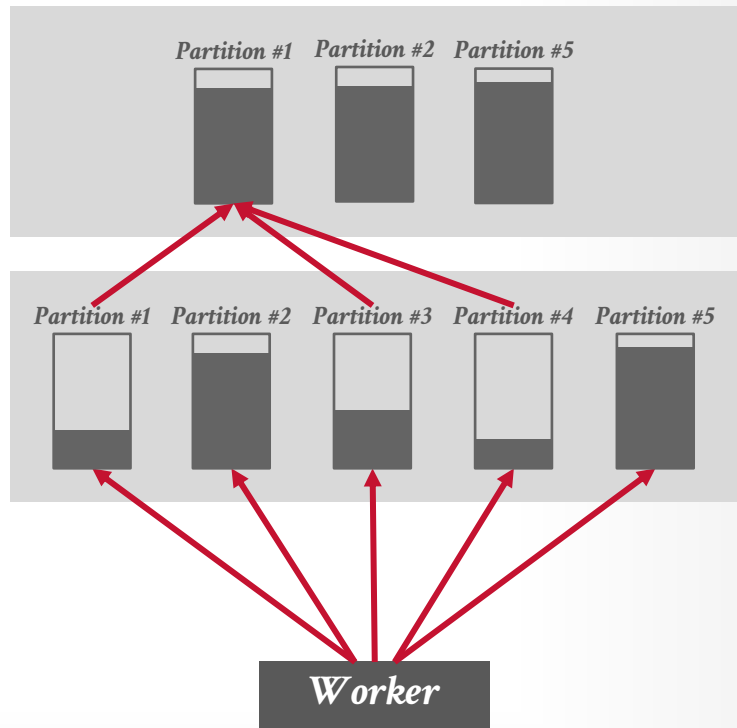
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PHOTON: BATCH-LEVEL ADAPTIVITY

Custom Primitives for ASCII vs. UTF-8 Data

→ ASCII encoded data is always 1-byte characters, whereas UTF-8 data could use 1 to 4-byte characters.

Compact Sparse Vectors

→ Copy tuples to new vectors before probing hash tables to maximize SIMD utilization.

No NULL Values in a Vector

→ Elide branching to checking null vector

No Inactive Rows in Vector

→ Elide indirect lookups in position lists

```

template <bool kHasNulls, bool kAllRowsActive>
void SquareRootKernel(const int16_t* RESTRICT pos_list,
int num_rows, const double* RESTRICT input,
const int8_t* RESTRICT nulls, double* RESTRICT result) {
for (int i = 0; i < num_rows; i++) {
    // branch compiles away since condition is
    // compile-time constant.
    int row_idx = kAllRowsActive ? i : pos_list[i];
    if (!kHasNulls || !nulls[row_idx]) {
        result[row_idx] = sqrt(input[row_idx]);
    }
}
}

```

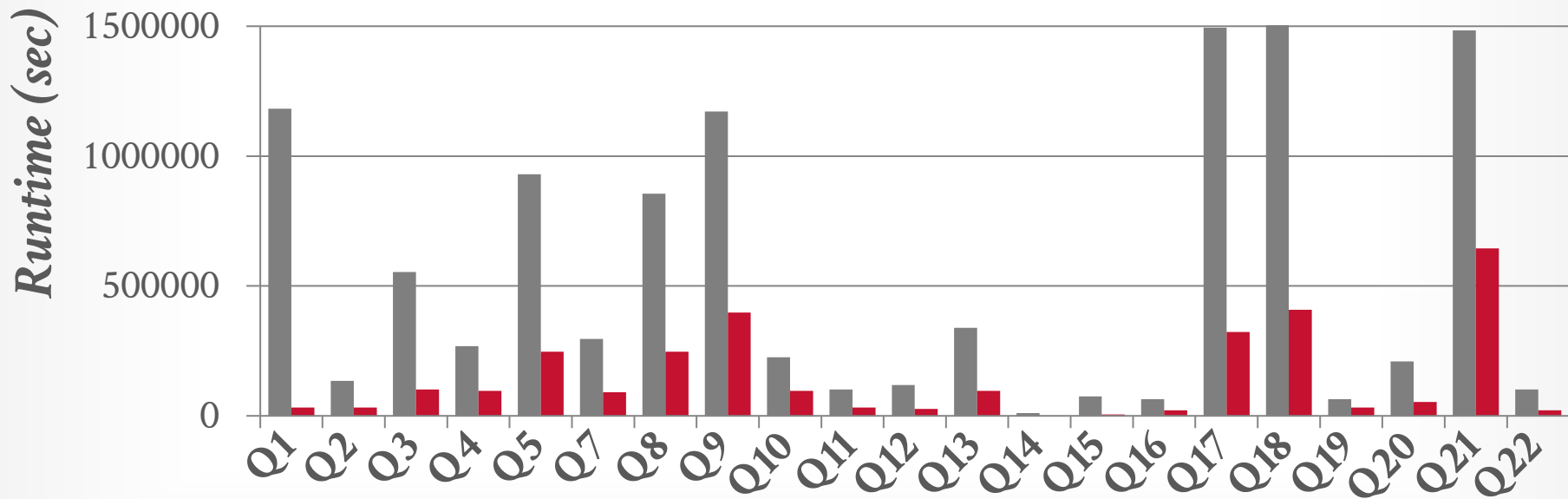
TPC-H COMPARISON

Databricks 8 nodes + 1 driver

Scale Factor = 3000

■ Spark SQL

■ Photon



DATABRICKS TPC-DS (2021)

Databricks announced audited TPC-DS results in late 2021.

DATABRICKS TPC-DS (2021)


























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TPC-DS V3 All Results - Sorted by Performance

Version 3 Results As of 12-Apr-2023 at 3:50 PM [GMT]

Note 1: TPC-DS Version 2 and TPC-DS Version 3 are **NOT** comparable.
Note 2: The TPC believes it is **NOT** valid to compare prices or price/performance of results in different currencies.
Note 3: The TPC believes that comparisons of TPC-DS results measured against different database sizes are misleading and discourages such comparisons. The TPC-DS results shown below are grouped by database size to emphasize that only results within each group are comparable.

10,000 GB Results

Company	System	v Performance (QphDS)	Price/kQphDS	Watts/KQphDS	System Availability	Database	Operating System	Date Submitted	Cluster
	Alibaba Cloud AnalyticDB	18,998,559	59.27 CNY	NR	06/17/20	Alibaba Cloud AnalyticDB 3.0.12	Alibaba Group Enterprise Linux Server 7.2 (Paladin)	06/17/20	Y
	Alibaba Cloud E-MapReduce	11,569,838	237.03 CNY	NR	04/17/20	Alibaba Cloud E-MapReduce 4.0.1	CentOS Linux Release 7.4	04/16/20	Y
	H3C UniServer R4900 G3	8,944,478	423.13 CNY	NR	12/23/20	GBase 8a V9	Red Hat Enterprise Linux Server 7.8	12/23/20	Y
	Supernico A+ Server 2123BT-HNC0R	4,418,054	110.29 USD	NR	08/31/19	Transwarp ArgoDB V1.2.1	Red Hat Enterprise Linux Server 7.6	08/07/19	Y

100,000 GB Results

Company	System	v Performance (QphDS)	Price/kQphDS	Watts/KQphDS	System Availability	Database	Operating System	Date Submitted	Cluster
	Databricks SQL 8.3	32,941,245	157.57 USD	NR	11/02/21	Databricks Photon Engine 8.3	Ubuntu 18.04.5 LTS	11/02/21	Y
	Alibaba Cloud E-MapReduce	14,861,137	175.23 USD	NR	09/16/19	Alibaba Cloud E-MapReduce 3.21.2	CentOS Linux Release 7.4	09/16/19	Y

'NR' in the Watts/KQphDS column indicates that no energy data was reported for that benchmark.

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TPC-DS V3 All Results - Sorted by Performance

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H3C	H3C UniServer R4900 G3	8,944,478	423.13 CNY	
SUPERMICRO	Supermicro A+ Server 2123BT-HNC0R	4,418,054	110.29 USD	

100,000 GB Results

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'NR' in the Watts/KQphDS column indicates that no energy data was reported for that benchmark.



ENTERPRISE

Databricks is gunning for Snowflake's core business

In a shot across the bow to Snowflake, Databricks is set to announce on Tuesday that its flagship data warehouse product has achieved record performance levels.



Databricks is poised to announce that an independent industry group validated results which show that Databricks' systems outperformed the closest data warehouse competitor by 2.2x. | Photo: Databricks

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And only old people care about official TPC results!

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SPARK ACCELERATORS

Since Photon is proprietary, there are other open-source alternatives to accelerate Spark's runtime.

These systems redirect entire query plans to separate runtime engines rather than use Photon's fine-grain integration.

Notable Examples:

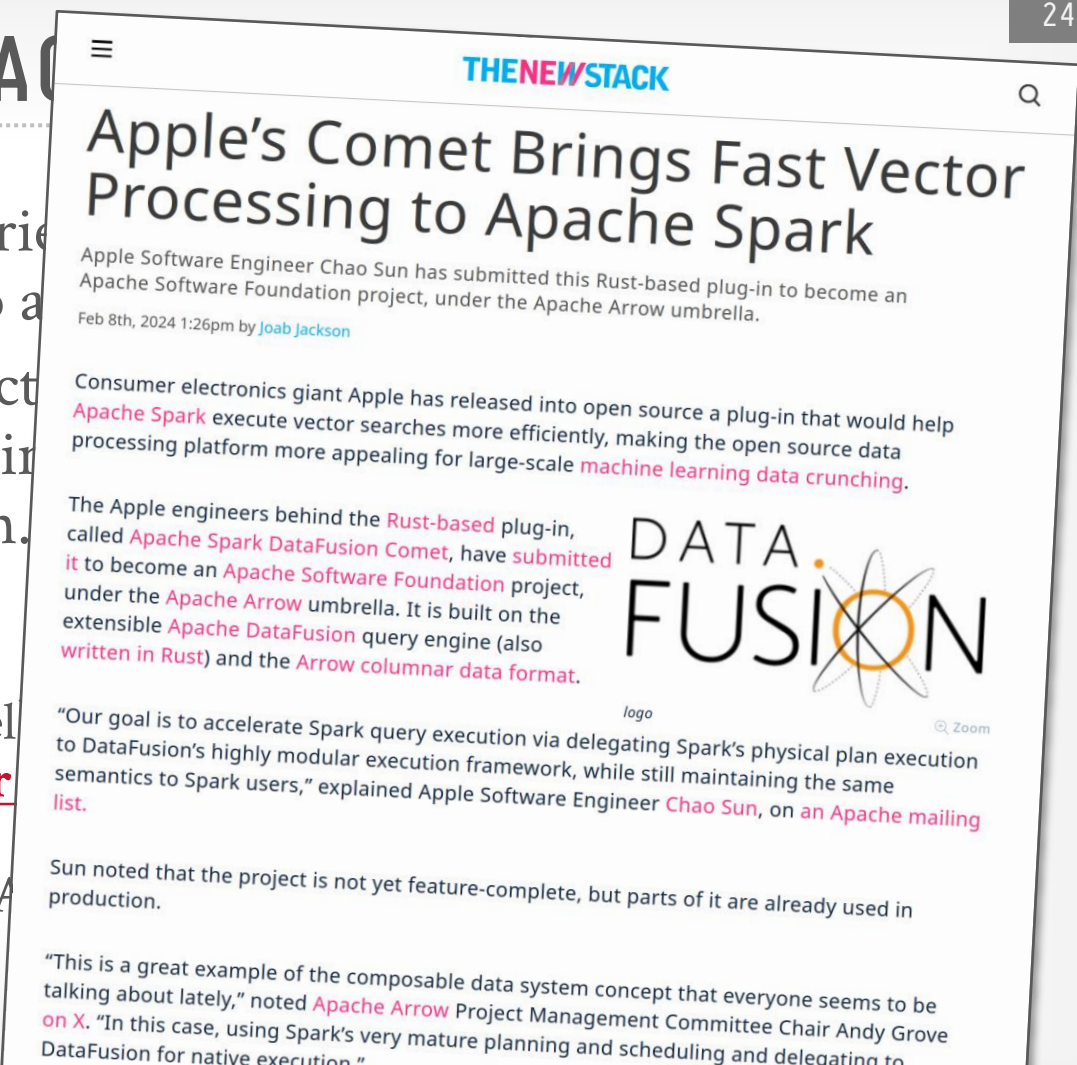
- [Apache Gluten](#) (Intel)
- [RAPIDS Accelerator for Spark](#) (Nvidia)
- [Blaze](#) (Kuaishou)
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SPARK AC

Since Photon is proprietary, there are open source alternatives to a Photon-like system. These systems redirect the execution of separate runtime engines to the Spark fine-grain integration.

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OBSERVATION

The lack of statistics makes query optimization harder for queries on data lakes. Adaptivity helps for some things, but the DBMS can do a better job if it knows something about the data.

What if there was a storage service for data lakes that supported incremental changes so that the DBMS could compute statistics?

DELTA LAKE (2019)

Transactional CRUD interface for incremental data ingestion of structured data on top of object stores.



DBMS appends writes to a JSON-oriented log.

Background worker periodically convert log into Parquet files (with computed statistics).

APACHE KUDU (2015)

Storage engine for low-latency random access on structured data files in distributed file system.

- Updates are written to in-memory B+tree and then converted to column store when written to disk.
- Vectorized execution for analytical queries.



No SQL interface (must use Impala). Only supports low-level CRUD operations.

 KUDU: STORAGE FOR FAST ANALYTICS ON FAST DATA
WHITE PAPER 2015

APACHE HUDI (2016)

Transactional (MVCC) system for incremental data ingestion of structured data on top of object stores.



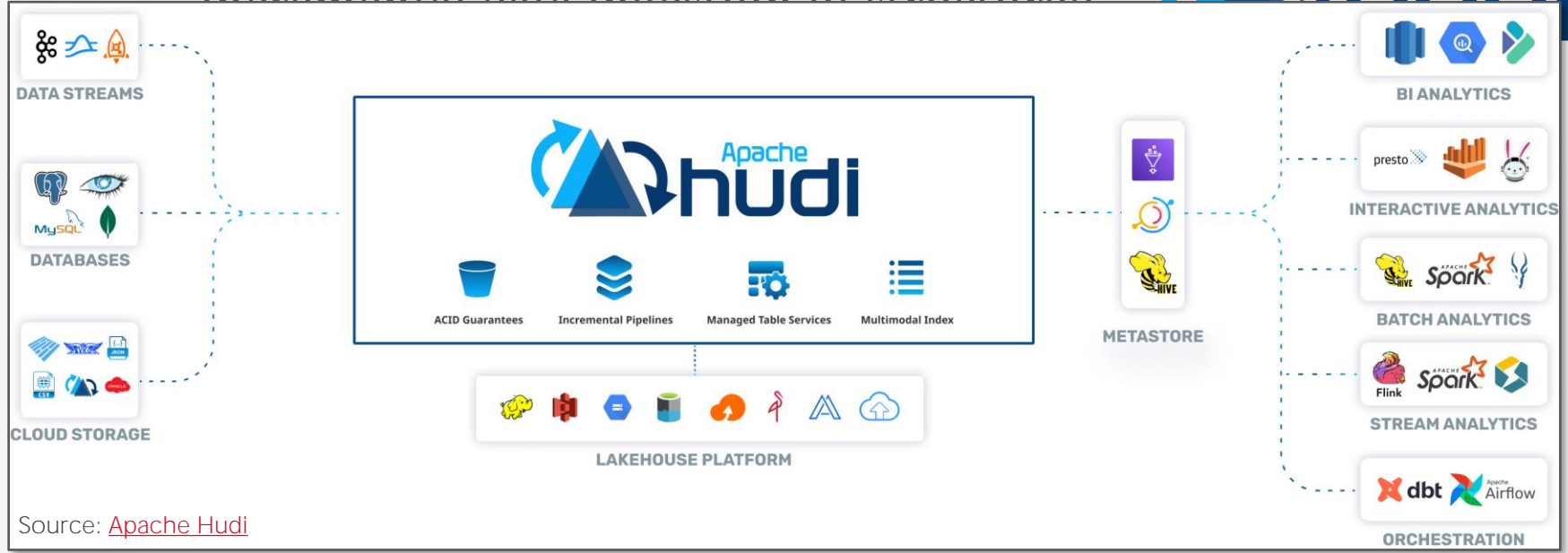
- Keeps track of partitioning, versioning, and schema changes. Background compaction.
- Provides catalog service for runtime lookups and pruning of meta-data.
- Supports both Parquet + ORC file formats.

Supports data ingestion from multiple sources:

- Examples: Kafka, Spark SQL, Flink SQL

APACHE HUDI (2016)

Transactional (MVCC) system for incremental data ingestion of structured



Source: [Apache Hudi](https://hudi.apache.org/)

APACHE ICEBERG (2017)

Infrastructure and file format extension to Parquet for maintaining catalog about data files in an object store.



- Keeps track of partitioning, versioning, and schema changes.
- Provides catalog service for runtime lookups and pruning of meta-data.

Snowflake added support for ingesting, creating, and querying Iceberg files in 2021.

PARTING THOUGHTS

The interesting parts of Photon is in its use of precompiled primitives and its integration with an existing JVM-based runtime infrastructure.

Andy does not recommend building a Java OLAP engine from scratch.

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NEXT CLASS

Snowflake